

ROBOT SPECIFICATIONS 2023 CATALOG



Why Epson® Robots?

As precision automation specialists, the Epson Robots team has been building automation products for nearly four decades. An industry leader in small-parts-assembly applications, we've introduced many firsts. As a result, our innovative products are hard at work in thousands of manufacturing facilities throughout the world.

Leading Epson technology

- Epson is the #1 SCARA robot manufacturer in the world
- We introduced the world's first folding-arm 6-Axis robot
- Specialized integrated motion sensors help reduce vibration and increase performance

What you need, when you need it

- The Epson lineup features 6-Axis and SCARA robots with payloads up to 20 kg and a reach ranging from 175 mm to 1,480 mm
- We offer a wide range of fully integrated options including vision guidance, conveyor tracking, flexible parts feeding, force guidance and more

Intuitive programming software

- Epson RC+® software is extremely user-friendly, making automation setup fast and easy
- It includes time-saving features such as wizards, templates, smart tools and more

Reliability you can count on

- Dedicated to helping you find the best solution for your automation needs
- Epson robots are long-lasting and require little maintenance
- Over 150,000 robots sold worldwide



Anti-static robots



C-SERIES

6-AXIS ROBOTS



C4

Compact robots with high repeatability and fast cycle times



C8

Powerful robots with long reach and heavy payloads



C12

High-performance robots with heavy payload and second-generation GYROPLUS Technology



C-SERIES SPECIFICATIONS

		C4	C8	C12		
Arm length		600/900 mm	700/900/1,400 mm	1,400 mm		
Repeatability	Joints #1 - #6	±0.020/±0.030 mm	±0.020/±0.030/±0.050 mm	±0.050 mm		
Payload	Rated	1 kg	3 kg	3 kg		
	Maximum	4 kg (5 kg with arm-downward positioning)	8 kg	12 kg		
Standard cycle time ¹		0.37/0.47 sec	0.31/0.35/0.53 sec	0.50 sec		
Installation environments		Standard/Cleanroom ISO Class 3 and 4 with ESD	Standard/Cleanroom ISO Class 3 and 4 with ESD/Protected IP67	Standard/Cleanroom ISO Class 4 with ESD		
Available controllers		RC700A				

¹ Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 1 kg payload (path coordinates optimized for maximum speed).

C-SERIES 6-AXIS ROBOTS





Scan Here for CAD Drawings

High speed and exceptional flexibility

- Arm lengths of 600 and 900 mm
- Payloads up to 4 kg
- Slim design and compact wrist—fits in tight spaces
- Cleanroom ISO Class 3 models available



SPECIFICATIONS

		C4-A601 (C4)		C4-A90	C4-A901 (C4L)	
Mounting type		Tabletop	Ceiling	Tabletop	Ceiling	
Degree of freedom				6		
Arm length	P Point: through the	600 mm		900 mm		
	center of J4/J5/J6					
Wrist flange surface		665 mm		965 mm		
Weight (cables not included)		27 kg		29 kg		
Repeatability	Joints #1 - #6	±0.020 mm		±0.030 mm		
Max. motion range	Joint #1	±170 deg				
	Joint #2	-160 ~ +65 deg				
	Joint #3	-51 ~ +225 deg				
	Joint #4	±200 deg				
	Joint #5	±135 deg				
	Joint #6	±360 deg				
Payload	Rated	1 kg				
	Maximum	4 kg				
tandard cycle time ¹		0.37 sec		0.47	0.47 sec	
Allowable moment	Joint #4	0.150 kg•m²				
of inertia²	Joint #5	0.150 kg•m²				
	Joint #6	0.100 kg•m²				
Electric lines		9-Pin (D-Sub)				
Pneumatic lines		Φ4 mm × 4				
Installation environments		Standard/Cleanroom ISO Class 3 with ESD				
Available controllers		RC700A				
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive				
		UL1740 ANSI/RIA R15.06				
		ANSI/HIA H 15.06 NFPA 79				
			INI	17170		

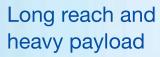
¹ Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 1 kg payload (path coordinates optimized for maximum speed).

² If the center of gravity is at the center of each arm. If the center of gravity is not at the center of each arm, set the eccentric quantity using the INERTIA command.

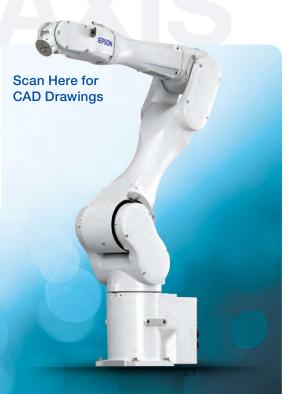
C8/C12







- Arm lengths of 700, 900 and 1,400 mm
- Payloads up to 12 kg
- Slim design and compact wrist—fits in tight spaces
- Cleanroom ISO Class 3 (C8/C8L) and Class 4 (C8XL/ C12XL) models available



SPECIFICATIONS

		C8-A701 (C8)	C8-A901 (C8L)	C8-A1401 (C8XL)	C12XL-A1401 (C12XL)			
Mounting type		Tabletop/Ceiling/Wall			Tabletop			
Degree of freedom		6						
Arm length	P Point: through the center of J4/J5/J6	711 mm	901 mm	1,400 mm	1,400 mm			
Wrist flange surface		791 mm	981 mm	1,480 mm	1,480 mm			
Weight (cables not included)		49 kg (Protected: 53 kg)	52 kg (Protected: 56 kg)	62 kg (Protected: 66 kg)	63 kg			
Repeatability	Joints #1 - #6	±0.02 mm	±0.03 mm	±0.05 mm	±0.05 mm			
Max. motion range	Joint #1	±240 deg						
	Joint #2	-158 ~ +65 deg -135			5 ~ +55 deg			
	Joint #3	-61 ~ +202 deg						
	Joint #4	±200 deg						
	Joint #5	±135 deg						
	Joint #6	±360 deg						
Payload	Rated	3 kg						
	Maximum	8 kg			12 kg			
Standard cycle time ¹		0.31 sec	0.35 sec	0.53 sec	0.50 sec			
Allowable moment	Joint #4	0.470 kg•m²			0.700 kg•m²			
of inertia ²	Joint #5	0.470 kg•m²			0.700 kg•m²			
	Joint #6		0.200 kg•m²					
Electric lines	Electric lines		15-Pin (D-Sub), 8-Pin (RJ45), 6-Pin (for Force Sensor)					
Pneumatic lines		Φ6 mm x 2						
Installation environments		Standard/Clear	Standard/Cleanroom ISO Class 4 with ESD					
Available controllers		RC700A						
Safety standards		CE Mark: EMC Directive, Machinery Directive, RoHS Directive UL1740 ANSI/RIA R15.06 NFPA 79			CE Mark: EMC Directive, Machinery Directive, RoHS Directive ANSI/RIA R15.06 NFPA 79			

¹ Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 1 kg payload (path coordinates optimized for maximum speed).

² If the center of gravity is at the center of each arm. If the center of gravity is not at the center of each arm, set the eccentric quantity using the INERTIA command.